

Deep Learning

7.1 Transposed Convolutions

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- 3 Convolutions, pooling, etc. reduce the signal dimension
- Transposed Convolutions increase the output size

Revisit Convolution in deep learning

1 1D convolution $x \circledast y$

$$y_i = \sum_{a} x_{i+a-1} k_a$$
$$= \sum_{u} x_u k_{u-i+1}$$

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② Backpropagating through convolution

$$\begin{split} \frac{\partial l}{\partial x} \Big]_{u} &= \left[\frac{\partial l}{\partial x_{u}} \right] \\ &= \sum_{i} \frac{\partial l}{\partial y_{i}} \frac{\partial y_{i}}{\partial x_{u}} \\ &= \sum_{i} \frac{\partial l}{\partial y_{i}} k_{u-i+1} \end{split}$$

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3 This also looks like convolution, but the kernel is visited in the reverse order

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dlc-7.1/Transposed Convolutions



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③ Therefore the backprop in convolution becomes

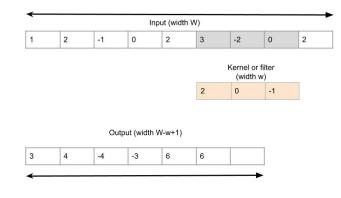
$$\begin{array}{l} \text{if } y = x \circledast k, \\ \text{then } \left[\frac{\partial l}{\partial x} \right] = \left[\frac{\partial l}{\partial y} \right] \ast k \end{array}$$

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1D convolution example





1D Convolution as matrix operation

$$\begin{bmatrix} 2 & 0 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 2 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ -1 \\ 0 \\ 2 \\ 3 \\ -2 \\ 0 \\ 2 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \\ -4 \\ -3 \\ 6 \\ 6 \\ -6 \end{bmatrix}$$



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- F.conv_transpose1d implements this operation.

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1 Increases the signal dimension



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- ② Used in Deep generative models