

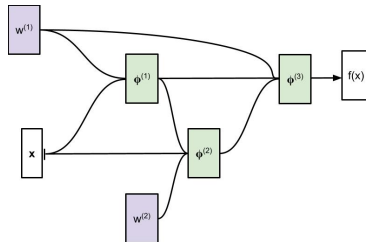
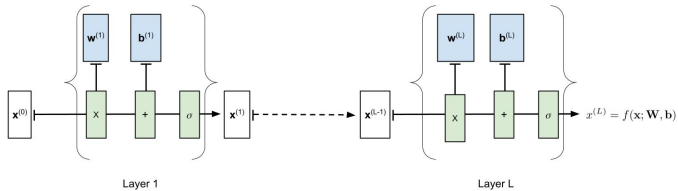
Deep Learning

3.6 Backprop beyond MLP and Autograd

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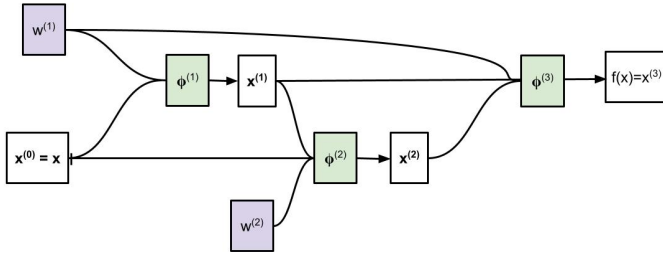
Beyond MLP

① We can generalize MLP



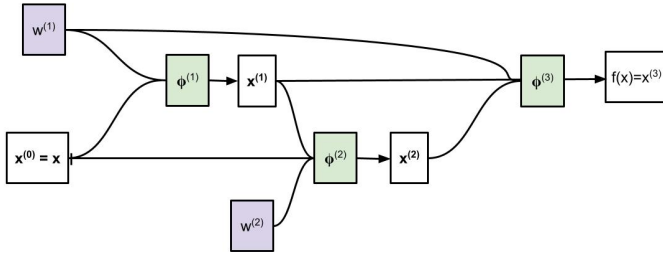
To an arbitrary Directed Acyclic Graph (DAG)

Forward pass in the computational graph



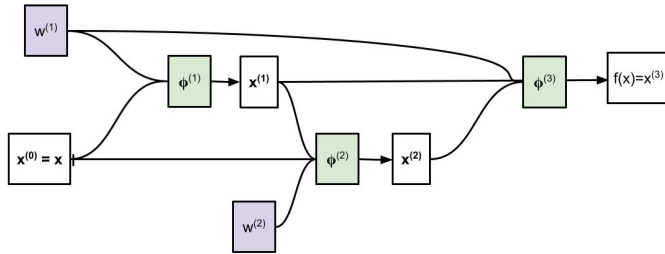
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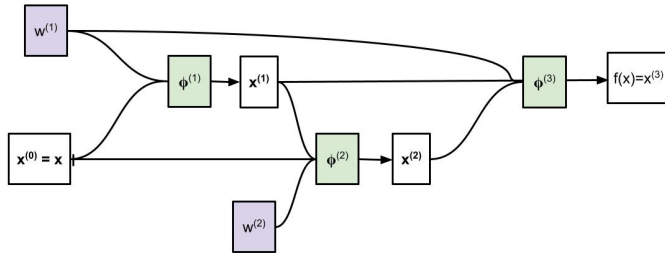
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Forward pass in the computational graph



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- ③ $x^{(2)} = \phi^{(2)}(x^{(0)}, x^{(1)}; w^{(2)})$
- ④ $f(x) = x^{(3)} = \phi^{(3)}(x^{(1)}, x^{(2)}; w^{(1)})$

Notation: Jacobian of a general transformation

①

if $(a_1 \dots a_Q) = \phi(b_1 \dots b_R)$ then we use the notation (1)

$$\left[\frac{\partial a}{\partial b} \right] = J_{\phi}^T = \begin{bmatrix} \frac{\partial a_1}{\partial b_1} & \cdots & \frac{\partial a_Q}{\partial b_1} \\ \vdots & \ddots & \vdots \\ \frac{\partial a_1}{\partial b_R} & \cdots & \frac{\partial a_Q}{\partial b_R} \end{bmatrix} \quad (2)$$

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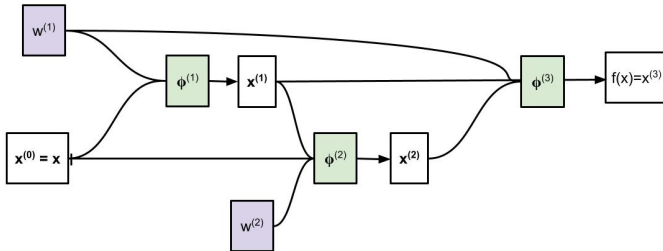
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if $(a_1 \dots a_Q) = \phi(b_1 \dots b_R; c_1 \dots c_S)$ then we use the notation (3)

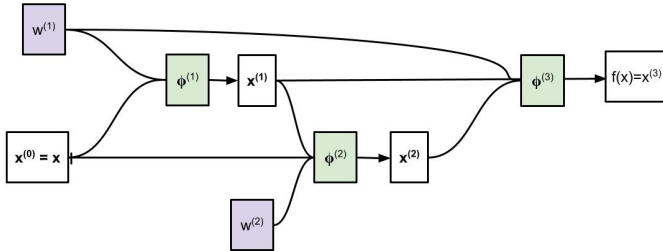
$$\left[\frac{\partial a}{\partial c} \right] = J_{\phi|c}^T = \begin{bmatrix} \frac{\partial a_1}{\partial c_1} & \cdots & \frac{\partial a_Q}{\partial c_1} \\ \vdots & \ddots & \vdots \\ \frac{\partial a_1}{\partial c_S} & \cdots & \frac{\partial a_Q}{\partial c_S} \end{bmatrix} \quad (4)$$

Backward pass



① From the loss equation, we can compute $\left[\frac{\partial \ell}{\partial x^{(3)}} \right]$

Backward pass

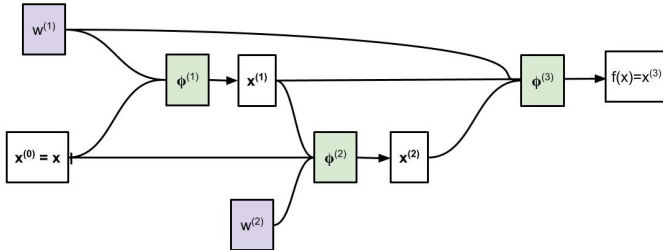


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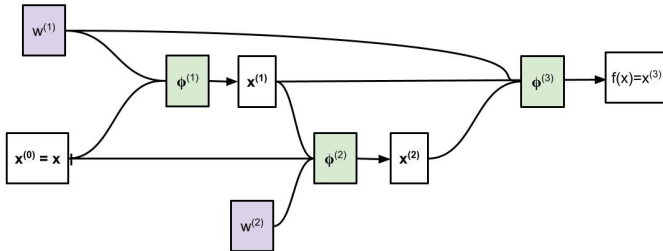
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$$\begin{aligned} \left[\frac{\partial \ell}{\partial x^{(1)}} \right] &= \left[\frac{\partial x^{(3)}}{\partial x^{(1)}} \right] \left[\frac{\partial \ell}{\partial x^{(3)}} \right] + \left[\frac{\partial x^{(2)}}{\partial x^{(1)}} \right] \left[\frac{\partial \ell}{\partial x^{(2)}} \right] \\ &= J_{\phi^{(3)}|x^{(1)}}^T \left[\frac{\partial \ell}{\partial x^{(3)}} \right] + J_{\phi^{(2)}|x^{(1)}}^T \left[\frac{\partial \ell}{\partial x^{(2)}} \right] \end{aligned}$$

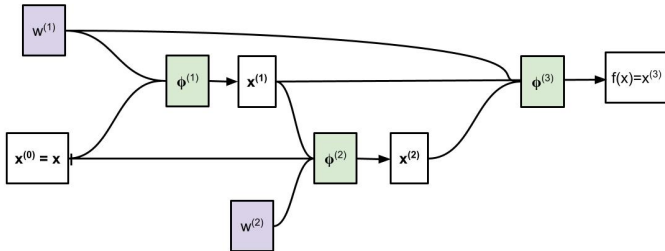
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1

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Backward pass



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2

$$\left[\frac{\partial \ell}{\partial w^{(2)}} \right] = \left[\frac{\partial x^{(2)}}{\partial w^{(2)}} \right] \left[\frac{\partial \ell}{\partial x^{(2)}} \right] = J_{\phi^{(2)}|w^{(2)}}^T \left[\frac{\partial \ell}{\partial x^{(2)}} \right]$$

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Autograd

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- ② Flexible: Computational graph can be dynamic, so is the forward pass

Autograd in PyTorch

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- ③ Default is False
- ④ `requires_grad_()` function can be used to set to any value

- ① `torch.autograd.grad(o/p, i/p)` returns gradients of outputs wrt the inputs

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- ③ Standard function used to train the models.
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- ⑤ Accumulation is helpful (e.g. sum of losses, or sum over different mini-batches, etc.)

`torch.no_grad()`

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- ② Useful for operations such as parameter updation

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- ③ Used when gradient should not be propagated beyond a variable, or to update the leaf nodes in the graph

Some Notes

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- ③ Graph can compute on the gradient tensor also, and Autograd can compute higher-order derivatives
- ④ Specified with `create_graph = True`

Demo

▶ Colab Notebook: Backword()